

# GUJARAT TECHNOLOGICAL UNIVERSITY

## B.E Semester: 4 Mechanical Engineering

Subject Code 141902  
Subject Name KINEMATICS OF MACHINES

Sr.No	Course content
1.	<b>Mechanism &amp; Machines:</b> Terminology and Definitions, Mechanism & Machines. rigid and resistance body, link, Kinematic pair Types of motion, degrees of freedom, classification of Kinematic pairs, Kinematic Chain, Linkage, Mechanisms, Kinematic Inversion of Single and Double slider crank Chain, Four bar Chain Mechanism with lower pairs, Straight line mechanism and approximate straight line mechanism such as Paucellier, Hart's mechanism, Watt, Modified Scott- Russel, Grasshoper, Robert's mechanism, Hooke's Joint it's analysis, condition for equal speed of driven and driver shafts, Double Hooks Joint, Quick return mechanisms, Steering gear mechanisms such as Davis and Ackermann Steering gear.
2.	<b>Kinematics:</b> Displacement, velocity and acceleration and analysis in simple mechanisms, Graphical Method velocity and acceleration polygons, Instantaneous Centre of Velocity, Kennedy Theorem, Angular velocity ratio theorem, Kinematic analysis by Algebraic methods, Vector Approach, Acceleration analysis, Klein's Construction, Coriolis Acceleration. Computer aided Kinematic Analysis of Mechanism like Slider Crank Mechanism, Four-Bar Mechanism.
3.	<b>Belts, Ropes, Chains:</b> Introduction, belt and ropes drives, selection of belt drive, types of belt drives, V-belts, materials used for belt and rope drives, wire rope, Slip and Creep of belt, tensions for flat belt drive, angle of contact, centrifugal tension, maximum tension of belt, Chains, Classification, length, angular speed ratio, classification of chains.
4.	<b>Gears &amp; Gear Trains:</b> Introduction, Classification of Gears, Gear Terminology, Law of Gearing, Velocity of Sliding, Forms of teeth, Cycloidal Profile Teeth, Both of Contact, Arc of the contact, Numbers of pairs teeth in contact, Interference in involutes gears, Minimum Number of teeth, Interference between Rack and Pinion, Under cutting, Comparison of Cycloidal and involutes tooth forms, Efficiency of Helical, Spiral, Worm, Worm Gear, and Bevel Gears. Simple, Compound, Reverted, Epicyclic gear train.
5.	<b>Cams:</b> Introduction, Definitions of cam and followers their uses, Types of Cams, Types of Followers and their motion, Cam Terminology, Displacement Diagrams, Motion of the Followers, Analysis of motion of followers : Roller follower, circular cam with straight, concave and convex ,flanks Graphical Construction of the Profile
6.	<b>Friction:</b> Surface contacts, Types of friction, Friction in screws with square thread and V threads, Pivot and collar friction, Friction clutches-single, multi-plate, cone clutch, Friction aspects in Brakes, Film friction, greasy friction

## Reference Books:

1. Shigley, J.E and Uicker, J.J: Theory of Machines and Mechanisms, Oxford University Press
2. Rattan S.S.: Theory of Machines Tata McGraw-Hill Publishing Co. Ltd. New Delhi,
3. Rao J.S. and Duddipati R.V: Mechanisms and theory Machines theory, Wiley Eastern Ltd.
4. Mabie H.H and Ocvirk, F.W: Kinematic and Dynamics of Machinery, 3<sup>rd</sup> Edition ,John wiley and sons.
5. Green, W.G: Theory of Machines, 2<sup>nd</sup> Edition, Blackie, London, 1992.
6. Hollownko, A.R: Dynamics of Machinery, John wiley and sons. Inc. New York, 1955.
7. Wilson, Kinematics and Dynamics of Machinery, 3<sup>rd</sup> Edition, Pearson Education.
8. Bevan Thomas, Theory of Machines